Notes for setup:

- Step 1 Set the frog polarity if it is the wrong way round reverse, the connection on the point motor, DCC In.
- Step 2 Set the correct LM-iD to move the point the correct way, reverse the connections in PBS-L & PBS-R.
- Step 3 Set the loop polarity, swap connections X1 and X2 if required see middle right on diagram.

